

SAC1

Motor controller for small vehicles and boats

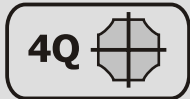
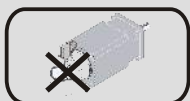
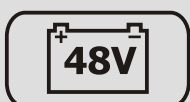
MAIN FEATURES

- State of the art technology
- Compact design
- Easy setup
- Sensorless vector control
- Speed or torque control
- Set-point value analog or via CAN bus
- Autotuning and self-test functions
- Battery management



TECHNICAL CHARACTERISTICS

- | | |
|--------------------------|--------------------------|
| ■ Battery voltage | 24 V to 48 V DC |
| ■ Rated output current | 50 A (75 A Option) |
| ■ Maximal output current | 110 A |
| ■ Rated power | 2.8 kVA (4.2 kVA Option) |
| ■ Maximal power | 6.5 kVA |



Technical specifications

Electrical data

Supply voltage	24 V to 60 V DC
Output frequency	0 Hz to 400 Hz (optionally up to 600Hz)
Interfaces	<ul style="list-style-type: none"> CAN RS232 interface for setup with the PC Software Motor temperature monitoring (PTC) HALL position sensor interface

Functions

Control method	<ul style="list-style-type: none"> Sensorless vector control (or combined with speed/position sensor) Torque or speed control
Operating functions	Speed mode with analog input, torque mode with analog input, constant speed operation, EV mode, CAN bus operation (speed or torque mode)
Braking functions	Generator braking (at speed limit, with analog input or with brake input)
Protections	Undervoltage, overvoltage, overcurrent, thermal motor protection, overtemperature, protection against battery deep-discharge and over-charge
Motor types	Asynchronous motors, permanent magnet synchronous motors with or without hall sensors

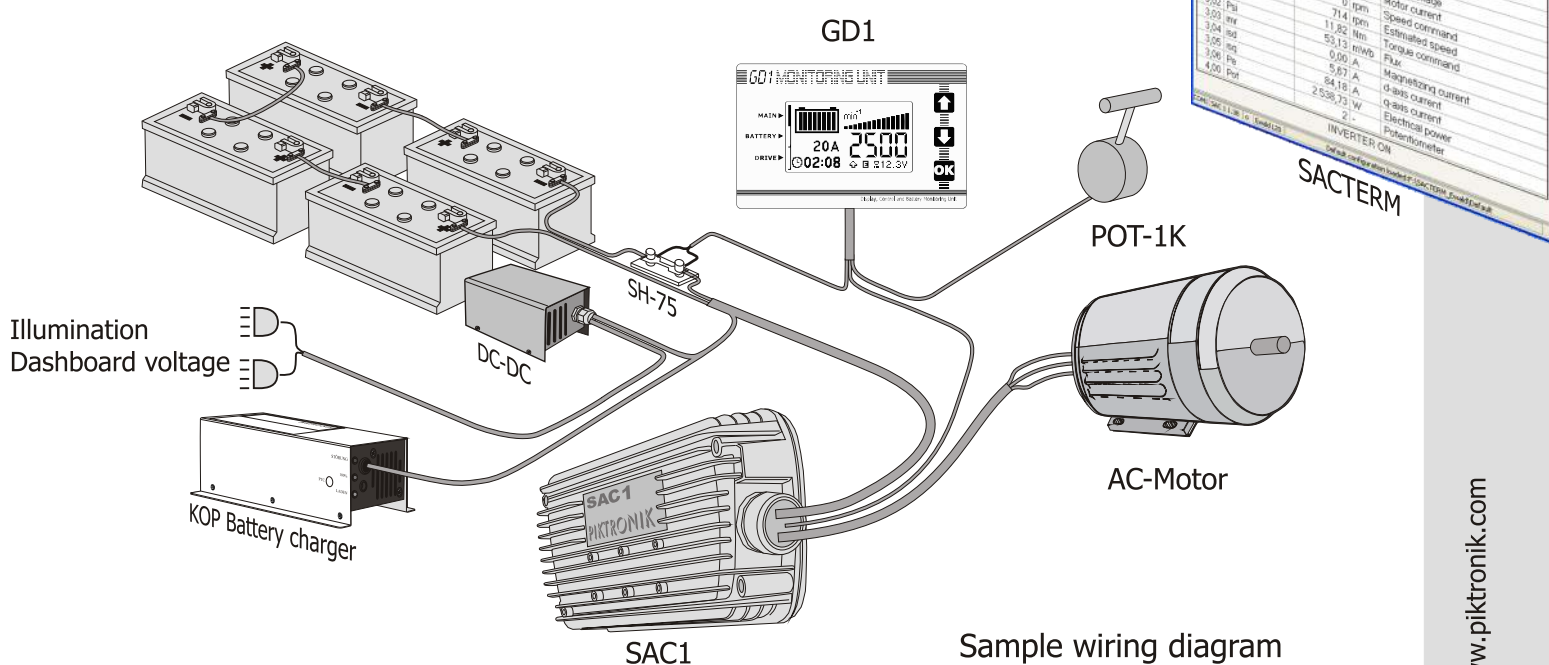
Mechanical data

IP enclosure rating	IP54
Ambient temperature	-25°C to +35°C
Size (L x W x H) in mm	300 x 140 x 65
Weight	2,4 kg

Optional accessories

- SACTERM setup, parametrization and diagnostics software
- GD1 display, control and battery monitoring unit

The desired performance features are binding only then if they were expressly agreed by contract.



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